

# Stable calibration methods for equity models of local Lévy type

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FFT and related issues  
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Joint work with S. Kindermann, H. Albrecher & H.W. Engl

# Outline

Motivation

The problem and a roadmap to the solution

An exemplary result

Generalisations and Applications

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# The usual way of pricing of derivatives

1. Model for the risk-neutral dynamics of the underlying asset (e.g. via stochastic differential equation)
2. Free (unknown) parameters in the model (e.g. volatility in BS-model)
3. Identification of parameters by observed option prices (Inverse Problem).
4. Calibrated model used for pricing illiquid derivatives (e.g. via MC-simulation, solving P(I)DE'S,...)

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## Problems:

- ✓ Data not exact (e.g. bid-ask-spreads)
- ✓ Discrete data sets (not complete option-price surface known)
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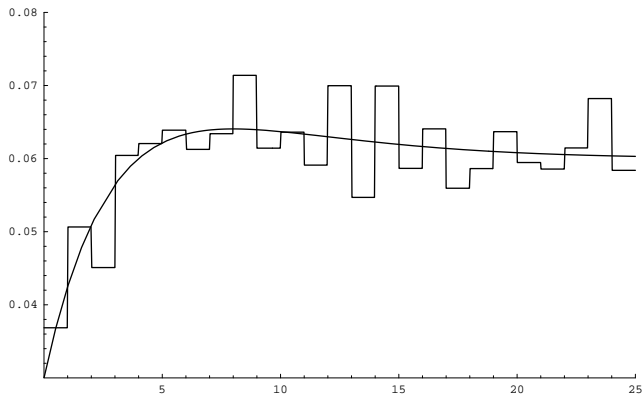
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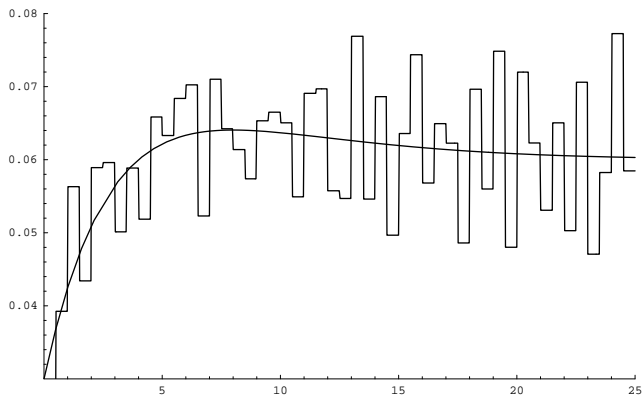
# What can happen with ill-posed problems?

Calculate (deterministic) short rate from given bond-prices  
(piecewise constant, noiselevel  $< 1\%$ )  
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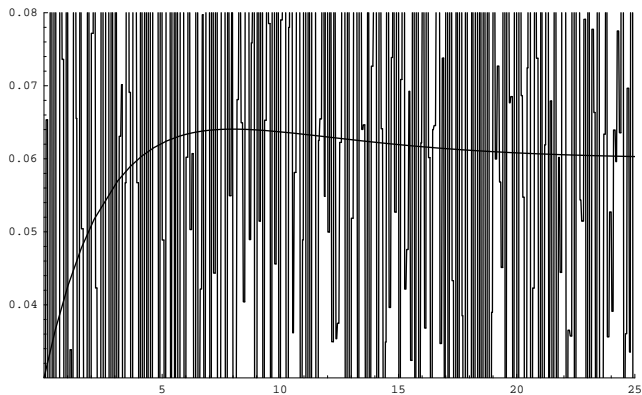
# What can happen with ill-posed problems?

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# How to circumvent the problems?

Facts:

- ✓ dangerous to fit in a naïve way
- ✓ more (noisy) data  $\Rightarrow$  more accurate results

Possible correction: Regularization

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# What has been done so far

Application of regularization in computational finance:

- ✓ *S. Crepey*: Calibration of the local volatility in a generalized Black-Scholes model using Tikhonov regularization. (2003)
- ✓ *H. Egger & H. W. Engl*: Tikhonov regularization applied to the inverse problem of option pricing: convergence analysis and rates. (2005)
- ✓ *R. Cont & P. Tankov*: Nonparametric calibration of jump-diffusion option pricing models. (2004)
- ✓ *R. Cont & P. Tankov*: Recovering exponential Lévy models from option prices: regularization of an ill-posed inverse problem. (2006)

# The well known local volatility model

Dupire (1994), Derman & Kani (1994):

$$dS_t = (r - \eta)S_t dt + \sigma(S_t, t)S_t dW(t),$$

$r$  riskless interest rate,  $\eta$  dividend yield

✓ capable of fitting marginal distributions of **any** Itô process (Gyöngy, 1986)

⇒ Parabolic PDE for call price

$$C_T + \eta C + (r - \eta)K C_K - \frac{1}{2} \sigma^2(K, T) K^2 C_{KK} = 0$$

$$C(0, K) = (S_0 - K)^+$$

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# Drawbacks of the local volatility model

- ✓ often very steep volatility structure
- ✓ Problems when pricing path-dependent options
- ✓ No jumps possible

Possible improvement: Lévy models

Advantages:

- ✓ jump-risk included
- ✓ fat tails
- ✓ skewed log-returns via asymmetric Lévy measure

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# Generalized Lévy models

In analogy to local volatility-models: **local Lévy model** (Carr et al. 2004)

► Parameter of Brownian motion & Lévy measure dependent on  $S_t$  and  $t$ :

$$dS_t = (r - \eta)S_{t-}dt + \sigma_0(S_{t-}, t)S_{t-}dW(t) \quad (1)$$

$$\int_{-\infty}^{\infty} (e^x - 1) (m_{(S_{s-}, s)}(dx, du) - \nu_{(S_{s-}, s)}(dx, du)) \quad (2)$$

$W$  ... Brownian motion

$m$  ... integer valued random measure independent of  $W$

$\nu$  ... its compensator

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# Special state-dependence of the Lévy measure

- ✓ Local volatility models: Brownian motion with variable speed (depending on local volatility function)
- ✓ Carr et al. variable speed of jump-part: local speed function

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# Solvability of the SDE

other representation:

$$S_t = S_0 e^{(r-\eta)t} e^{X_t},$$

where  $X_t$  is a semimartingal with characteristics

$$(-\sigma^2(\xi_{t-}, t)/2, \sigma(\xi_{t-}, t), a(\xi_{t-}, t)dt \times \nu),$$

where:  $\xi_t = \ln(S_0) + (r - \eta)t + X_t$ ,  $\sigma(x, t) = \sigma_0(e^x, t)$  and  $a(x, t) = a_0(e^x, t)$ .

**Note:** speed function **does not** affect the jump-size distribution

Existence results: e.g. Ethier & Kurtz (1986), Gihman & Skorohod (1979) under different conditions

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# Option price for local Lévy model I

Carr et al.: with Tanaka-Meyer formula partial integro-differential equation (PIDE) for callprice:

$$C_T = \eta C + (r - \eta) K C_K + \frac{\sigma^2(K, T)}{2} K^2 C_{KK} + \int_0^\infty Y C_{YY}(Y, T) a_0(Y, T) \psi_e \left( \log \left( \frac{K}{Y} \right) \right) dY$$

in the weak sense

# Option price for local Lévy model II

## Structure of Equation

$$C_T = -\eta C - (r - \eta)K C_K + \frac{\sigma_0^2(K, T)}{2} K^2 C_{KK} + \int_0^\infty Y C_{YY}(Y, T) a_0(Y, T) \psi \left( \log \left( \frac{K}{Y} \right) \right) dY$$

Black Scholes Part + Integral Operator with kernel  $\psi$

- ✓  $\sigma_0$  ... local volatility
- ✓  $a_0$  ... local speed function
- ✓  $\psi$  ... double exponential tail of Lévy measure

$$\psi(z) = \begin{cases} \int_{-\infty}^z (e^z - e^x) \nu(dx) & \text{for } z < 0 \\ \int_z^\infty (e^x - e^z) \nu(dx) & \text{for } z > 0. \end{cases}$$

# What is the task?

⇒ Parameter identification in a PIDE using partial knowledge of solution

For Black-Scholes:

$$\sigma^2(K, T) = 2 \frac{C_T - \eta C - (r - \eta) K C_K}{K^2 C_{KK}}$$

Problem:

Differentiation of Data  $C(K, T) \Rightarrow$  ill-posed (2 times differentiation)

- ✓ **Not stable** for noisy data
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# Finding the local speed function

Assume  $\sigma$  &  $\psi$  fixed:

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# Abstract formulation of the problem

Identification problem as operator equation:

$$F(\theta) = y$$

$$F : \theta \rightarrow C(K, T)$$

$F$  ... parameter to solution operator

$y$  ... data = (observed option prices)

$\theta$  ...  $(\sigma, a, \nu)$

Problem ►  $F$  does not have continuous inverse.

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# No direct solution - what else?

Wishlist:

- ✓ **Stability:** Computed solution should depend continuously on data
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Two demands are in opposition to each other

Regularization: compromise

Nonlinear Problem  $\Rightarrow$  Nonlinear Tikhonov Regularization

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# Tikhonov regularization

Find approximate solution by minimizing

$$J(\theta) := \|F(\theta) - y_\delta\|^2 + \alpha\|\theta - \theta^*\|^2$$

$y_\delta$  ... noisy data

$\delta$  ... noise level:  $\|y_\delta - y\| = \delta$

$\theta^*$  ... initial guess

$\|\cdot\|$  ... suitable norms

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# Convergence theory for Tikhonov regularization

Nonlinear Theory: Engl, Kunisch & Neubauer (1989), Engl, Hanke & Neubauer (1996)

Results:

If graph of  $F$  is weakly sequentially closed

- ✓ Minimizer of Tikhonov functional exists
- ✓ Minimizer depends continuously on data for  $\alpha > 0$
- ✓ For noise-free data: Minimizer converges to true parameter as  $\alpha \rightarrow 0$
- ✓ Noisy data: if  $\frac{\delta^2}{\alpha(\delta)} \rightarrow 0$ , regularized solution converges to true solution as noise level  $\delta \rightarrow 0$ .

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# Identification of the local speed function

Assume for some reasons  $\sigma > 0$ ,  $\psi$  fixed &  $T^*$  a finite planning horizon:

Operator equation:

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where  $y$  is the given data and  $F$  defined via PIDE

For applicability of Tikhonov regularization:

- ✓ Well-posedness of forward problem (cf. Matache et al. 2004, 2005)
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# Reparametrization of the call price

$$c^{(\theta)}(k, T) = e^{\eta T} C(e^k, T) - g(x),$$

where  $g(k) = (S - e^k)^+$

Introducing

$$\mathcal{I}_\psi u := \psi * u = \int_{-\infty}^{\infty} \psi(k - y) u(y) dy$$

$$\begin{aligned} \mathcal{L}_\theta u := & \left( r - \eta + \frac{\sigma^2(k, T)}{2} \right) u_k - \frac{\sigma^2(k, T)}{2} u_{kk} \\ & - \mathcal{I}_\psi (a(\cdot, T)(u_{kk} - u_k)) \end{aligned}$$

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# Existence and Uniqueness of PIDE solution

Assumptions:

$$\begin{aligned}\sigma(k, T) &\geq c_0 > 0 \in L^\infty([0, T^*], W^{1,\infty}(\mathbb{R})) \\ \sigma_k(k, T) &\in L^\infty([0, T^*], L^2(\mathbb{R})).\end{aligned}$$

(Positivity and Smoothness of volatility)

$$\begin{aligned}a_0(k, T) \geq 0 &\in L^\infty([0, T^*] \times \mathbb{R}), \\ a_k(k, T) &\in L^\infty([0, T^*], L^2(\mathbb{R})).\end{aligned}$$

(Positivity and Smoothness of local speed function)

$$\begin{aligned}\mathbb{E}[S_t \ln S_t] &< \infty, \quad 0 \leq t \leq T^* \\ &\text{(Regularity of } \nu)\end{aligned}$$

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# Existence and Uniqueness of PIDE solution

Assumptions:

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# Well-posedness of forward problem

Existence and Uniqueness by Gårding inequality:

Black Scholes Part:

$$c_T^{(\theta)} - \left( r - \eta - \frac{\sigma^2(k, t)}{2} \right) c_k^{(\theta)} + \frac{\sigma^2(k, T)}{2} c_{kk}^{(\theta)}$$

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Under assumptions on  $a$ ,  $\sigma$ ,  $\nu$ :

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- ✓  $c^{(\theta)}(K, T)$  is Frechet-differentiable with respect to  $a$
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⇒ Theory of Nonlinear Tikhonov Regularization is applicable

For our problem:

- ✓ **Existence** of a Minimizer
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$a^\dagger$  ... true solution

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# Interpretation of source condition I

- ✓ **Smother** range of  $F'^*(a^\dagger) \Rightarrow$  **sharper** the source condition.
- ✓ Smother  $F'^* \Rightarrow$  Problem more difficult

$$F'^*(a^\dagger) \sim K^2 C_{KK} \mathcal{I}(v)$$

$\mathcal{I}$  is integral operator with kernel  $\psi$

$v$  is solution to adjoint PIDE

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**degree of ill-posedness:** Ill-posedness of two problems can be compared:  
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Consequences from source condition

Multiplication part:

$$F'^*(a^\dagger) \sim K^2 C_{KK} I^* v$$

Wherever  $C_{KK}(K, T) = 0$  the exact solution has to be known!.

- ✓ Interpretation:  $C_{KK}(K, T) \sim$  density of  $S_T$
- ✓ If density is 0 at some  $K, T$  then speed function  $a_0(K, T)$  has no influence on solution.
- ✓  $\Rightarrow$  Not uniquely identifiable there.

For positive volatility  $\sigma_0 > 0$  density positive ( $C_{KK} > 0$ )

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# Comparison with local volatility model

source conditions of **local Lévy** and **local volatility**

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Identification for Local Lévy problem **more ill-posed** than local volatility identification (smoothing integral operator)

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# Ill-Posedness

For typical case  $\psi$ : jump at 0 (or not defined)

$$\int_0^{\infty} (e^x - 1)\nu(dx) \neq \int_{-\infty}^0 (1 - e^x)\nu(dx)$$

$\Rightarrow \mathcal{I}$  like a smoothing operator of order 1.

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$$a_{\alpha,\delta} = \operatorname{argmin}(\|F(a) - y_\delta\|^2 + \alpha\|a - a^*\|_S^2),$$

where  $\|\cdot\|_S$  the tensor product norm  $H^1[0, K_0] \otimes H^1[0, T]$

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- ✓ Discretization of PIDE (finite element + Crank Nicholson)
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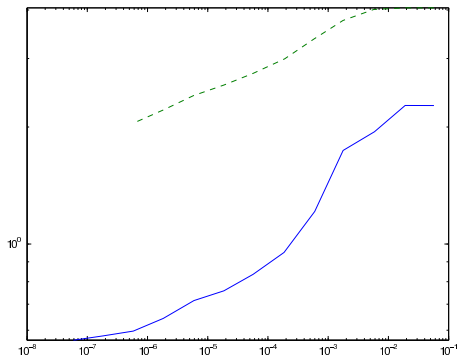
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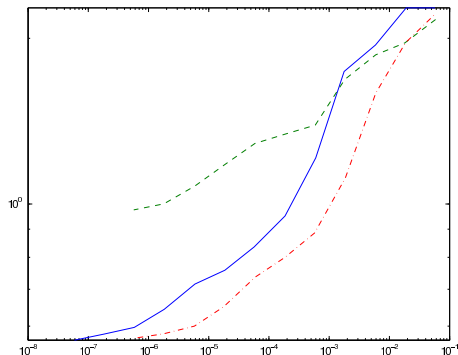
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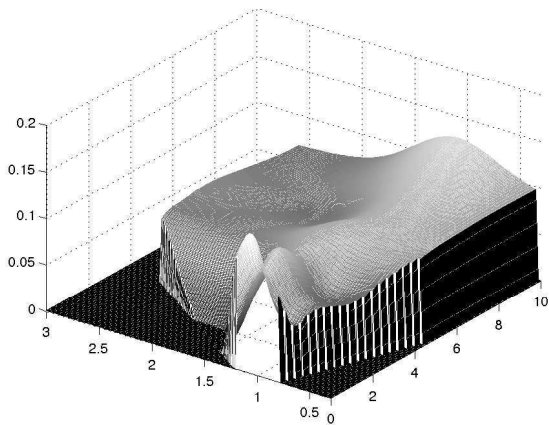
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# Numerical Computation Real data

Computed solution of local speed function: For Option price data from Andersen & Andreasen



# Outline

Motivation

The problem and a roadmap to the solution

An exemplary result

**Generalisations and Applications**

# Identification of $\sigma$

only  $\nu$  fixed

$\Rightarrow$  identify local volatility  $\sigma > 0$  & local speed function  $a$

Problem:

$$F(\sigma, a) = y$$

with same techniques, i.e. PIDE-methods & Tikhonov regularization, feasible

Frechet derivative:

- ✓ **exists**  $\Rightarrow$  computationally tractable
- ✓ **locally Lipschitz continuous**  $\Rightarrow$  convergence rates (if source condition met)

Application  $\Rightarrow$  local time for jump diffusion

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# Conclusions

- ✓ Nonlinear Tikhonov Regularization can be used as a stable and robust method for identifying parameters in financial stochastic differential equations.
- ✓ Identifying parameters in local Lévy model is more ill-posed than in local volatility model
- ✓ Theory of Tikhonov Regularization allows generalisation to other related parameter identification problems

Thank you for your attention!