# **Contagious default: application of methods of Statistical Mechanics in Finance**

Wolfgang J. Runggaldier University of Padova, Italy www.math.unipd.it/runggaldier

based on joint work with : Paolo Dai Pra, Elena Sartori (University of Padova) and Marco Tolotti (SNS Pisa and Bocconi University Milan)

AMAMEF, Vienna, September 20, 07

# Outline

- *The financial problem :* credit risk and the modeling of contagion
- The interacting particle system model
- The main results for the particle system

i) Asymptotics when the number of particles  $N \rightarrow \infty$ ii) Equilibria of the limiting dynamics iii) Finite volume approximations

• *Back to Finance :* large portfolio losses in a credit risky environment with contagion and default clustering.

### The financial problem : Credit risk

- Risk faced by a financial institution holding a portfolio of positions issued by a (large) number of firms that may default.
  - i) *Default* may be *contagious*
  - ii) There may be a *clustering of defaults* (many defaults happen in a short time)

Losses may therefore be large and we want to address this problem in the above context *(contagion and clustering)*.

• Reduced-form or intensity-based approach

### **Contagion** (interacting intensities)

- To describe propagation of financial distress in a network of firms linked (directly or indirectly) by business relationships one possibility is via interacting intensities.
  - $\rightarrow$  A natural way to obtain interacting intensities is to let the default intensities depend on a *common exogenous macroeconomic factor process*  $X_t$ , i.e. for the generic j-th firm one postulates

$$\lambda_t^j = \lambda^j(X_t)$$

- Given  $\lambda_t^j = \lambda^j(X_t)$ 
  - i) If  $X_t$  is observable and has jumps in common with the point process counting the defaults  $\rightarrow$  *direct contagion (counterparty risk)*
  - ii) If  $X_t$  is unobservable, but its distribution is successively updated on the basis of the observed default history  $\rightarrow$  *information induced contagion*.
- → Interacting intensity models are currently those mostly investigated and they are motivated by the empirical observation that default intensities are correlated with macroeconomic factors.

• However (quoting from Jarrow and Yu (2001)):

"A default intensity that depends linearly on a set of smoothly varying (exogenous) macroeconomic variables is unlikely to account for the clustering of defaults around an economic recession".

- Furthermore, one might also want to describe the general health of a network of firms by *endogenous financial indicators* thereby viewing *a credit crisis as a microeconomic phenomenon* and so possibly also arrive at explaining *default clustering*.
  - → Interacting particle system models from Statistical mechanics may allow to adequately address the above issues.

### The interacting particle system model

- A mean-field interacting model of the Curie-Weiss type; a simple model to describe dynamically the credit quality of firms.
- The "credit state" of each firm is identified by two variables  $(\sigma, \omega)$   $((\sigma_i, \omega_i)$  : state of i-th firm  $i = 1, \dots, N$ ).
  - → σ : a "rating class/financial distress indicator" (a low value reflects a bad rating class, i.e. a higher probability of not being able to pay back obligations).
     → ω : a more fundamental indicator of the financial health of the firm; (it represents a local random environment and is typically not directly observable from the market).

- At a first level assume  $(\sigma_i, \omega_i) \in \{-1, +1\}^2$ (generalization to a generic finite number of possible values rather straightforward)
- No explicit "default state" (could be  $\sigma_i = -1$ ). Always need a positive probability that the firm can exit from the state where  $\sigma_i$  takes its lowest possible value.

- For the time evolution on a generic interval [0,T] of the "state" of the particle system, i.e.  $(\sigma_i(t), \omega_i(t))_{i=1, \cdots, N} \in \mathcal{D}^{2N}[0,T]$  we need to specify the stochastic dynamics for the transitions  $\sigma_i \rightarrow -\sigma_i, \ \omega_i \rightarrow -\omega_i$ .
- The mean-field assumption leads to letting the interaction depend on the global health indicator (endogenous global factor)

$$m_N^{\underline{\sigma}}(t) := \frac{1}{N} \sum_{i=1}^N \sigma_i(t)$$

• The vehicle of interaction/contagion is given by

$$\omega_i \longrightarrow \sigma_i \longrightarrow m_N^{o} \longrightarrow \omega_j$$
fundam. indic. rating class global health indic.

### Transition intensities for the particle system

 $\begin{cases} \sigma_i \to -\sigma_i & \text{with intensity } \lambda_i := e^{-\beta \sigma_i \omega_i}, \quad \beta > 0\\ \omega_j \to -\omega_j & \text{with intensity } \mu_j := e^{-\gamma \omega_j m_N^{\sigma}}, \quad \gamma > 0 \end{cases}$ 

 $\beta, \gamma$  are parameters indicating the strength of the interaction (*This induces a "symmetry" in the model*).

 $\rightarrow$  The resulting transition intensity matrix can be taken as *infinitesimal generator* L of a *continuous-time Markov chain* with state space  $\{-1,+1\}^{2N}$  that acts on  $f: \{-1,1\}^{2N} \rightarrow \mathbb{R}$  as

$$Lf(\sigma,\omega) = \sum_{i=1}^{N} \lambda_i \nabla_i^{\sigma} f(\sigma,\omega) + \sum_{j=1}^{N} \mu_j \nabla_j^{\omega} f(\sigma,\omega)$$

where  $\nabla_i^{\sigma} f(\sigma, \omega) = f(\sigma^i, \omega) - f(\sigma, \omega); \quad \nabla_j^{\omega} f(\sigma, \omega) = f(\sigma, \omega^j) - f(\sigma, \omega)$ and  $\sigma^i = (\sigma_1, ..., \sigma_{i-1}, -\sigma_i, \sigma_{i+1}, ..., \sigma_N);$  analogously for  $\omega^j$ . • Unlike many mean field models in Statistical mechanics our *model is non-reversible*.

→ An explicit formula for the stationary (in time) distribution is not available.

- $\rightarrow~$  We shall rather
- **A.** Look for the *limit*  $(N \rightarrow \infty)$  *dynamics* of the system on the path space (via a LLN based on a Large Deviations Principle);
- **B.** Study the *equilibria of the limiting dynamics*;
- **C.** Describe "finite volume approximations" (for large but finite N) via a Central Limit type result.
- $\rightarrow$  Non-standard versions of LLN and CLT

A. Limit for  $N \rightarrow \infty$  (Law of Large Numbers)

• Let  $(\delta_{\{\cdot\}} \text{ denotes the Dirac measure})$ 

$$\rho_N = \frac{1}{N} \sum_{i=1}^N \delta_{\{\sigma_i[0,T],\omega_i[0,T]\}}$$

be the sequence of empirical (random) measures on the space  $\mathcal{M}_1(\mathcal{D}^2[0,T])$  endowed with the weak convergence topology.

• For a probability measure  $q \in \mathcal{M}_1(\{-1,1\}^2)$  let

$$m_q^{\sigma} := \sum_{\sigma, \omega = \underline{+}1} \sigma \, q(\sigma, \omega)$$

(expected health under q).

Theorem 1. Let  $(\sigma(t), \omega(t))$  be the Markov process corresponding to the generator  $Lf(\sigma, \omega)$  and with initial distribution s.t.  $(\sigma_i(0), \omega_i(0)), i = 1, \dots, N$  are i.i.d. with law  $\ell$ .

- i) There exists  $Q^* \in \mathcal{M}_1(\mathcal{D}^2[0,T])$  s.t.  $\rho_N \to Q^*$  a.s. in the weak topology;
- ii) if  $q_t \in \mathcal{M}_1(\{-1,1\}^2)$  is the marginal distribution of  $Q^*$  at time t, then it is the unique solution of the *McKean-Vlasov equation (MKV)*

$$\begin{cases} \frac{\partial q_t}{\partial t} = \mathcal{L}q_t, \quad t \in [0,T] \\ q_0 = \ell \end{cases}$$

with  $\mathcal{L}q(\sigma,\omega) = \nabla^{\sigma} \left[ e^{-\beta\sigma\omega}q(\sigma,\omega) \right] + \nabla^{\omega} \left[ e^{-\gamma\omega m_q^{\sigma}}q(\sigma,\omega) \right]$ 

## B. Large time behavior of the limiting $(N \rightarrow \infty)$ dynamics

• A measure  $\mu$  on  $\{-1,1\}^2$  is completely specified by

$$m_{\mu}^{\sigma} := \sum_{\sigma,\omega=\pm 1} \sigma \,\mu(\sigma,\omega), \\ m_{\mu}^{\omega} := \sum_{\sigma,\omega=\pm 1} \omega \,\mu(\sigma,\omega), \\ m_{\mu}^{\sigma\omega} := \sum_{\sigma,\omega=\pm 1} \sigma \omega \,\mu(\sigma,\omega), \\ m_{\mu}^{\sigma\omega} := \sum_{\sigma,\omega=\pm 1} \sigma \omega \,\mu(\sigma,\omega), \\ m_{\mu}^{\omega} := \sum_{\sigma,\omega=\pm 1} \sigma \,\mu(\sigma,\omega), \\ m_{\mu}^{\omega} := \sum_{\sigma,\omega=$$

Write 
$$m_t^{\sigma} = m_{q_t}^{\sigma}$$
 (analogously for  $m_t^{\omega}, m_t^{\sigma\omega}$ )

• (MKV) can be reduced to determining a solution of

$$(\dot{m}_t^{\sigma}, \dot{m}_t^{\omega}) = V(m_t^{\sigma}, m_t^{\omega})$$
 (mkv) with

 $V(x,y) := (2\sinh(\beta)y - 2\cosh(\beta)x, 2\sinh(\gamma x) - 2y\cosh(\gamma x))$ 

→ To analyze in (MKV) equilibria and their stability it suffices to analyze (mkv)

#### Theorem 2.

i) Suppose  $\gamma \leq \frac{1}{\tanh(\beta)}$ . Then equation (mkv) has (0,0) as a unique equilibrium solution, which is *globally* asymptotically stable, i.e. for every initial condition  $(m_0^{\sigma}, m_0^{\omega})$ , we have

$$\lim_{t \to +\infty} (m_t^{\sigma}, m_t^{\omega}) = (0, 0).$$

**ii)** For  $\gamma < \frac{1}{\tanh(\beta)}$  the equilibrium (0,0) is *linearly stable*, i.e. DV(0,0) (the Jacobian matrix) has strictly negative eigenvalues. For  $\gamma = \frac{1}{\tanh(\beta)}$  the linearized system has a neutral direction, i.e. DV(0,0) has one zero eigenvalue. iii) For  $\gamma > \frac{1}{\tanh(\beta)}$  the point (0,0) is still an equilibrium for (mkv), but it is a saddle point for the linearized system, i.e. the matrix DV(0,0) has two nonzero real eigenvalues of opposite sign. Moreover (mkv) has *two linearly stable solutions*  $(m_*^{\sigma}, m_*^{\omega})$ ,  $(-m_*^{\sigma}, -m_*^{\omega})$ , where  $m_*^{\sigma}$  is the unique strictly positive solution of the equation

$$x = \tanh(\beta) \tanh(\gamma x),$$

and

$$m_*^{\omega} = \frac{1}{\tanh(\beta)} m_*^{\sigma}$$

iv) For  $\gamma > \frac{1}{\tanh(\beta)}$ , the *phase space*  $[-1,1]^2$  *is bipartitioned* by a smooth curve  $\Gamma$  containing (0,0) such that  $[-1,1]^2 \setminus \Gamma$  is the union of two disjoint sets  $\Gamma^+, \Gamma^-$  that are open in the induced topology of  $[-1,1]^2$ . Moreover

$$\lim_{t \to +\infty} (m_t^{\sigma}, m_t^{\omega}) = \begin{cases} (m_*^{\sigma}, m_*^{\omega}) & \text{if } (m_0^{\sigma}, m_0^{\omega}) \in \Gamma^+ \\ (-m_*^{\sigma}, -m_*^{\omega}) & \text{if } (m_0^{\sigma}, m_0^{\omega}) \in \Gamma^- \\ (0, 0) & \text{if } (m_0^{\sigma}, m_0^{\omega}) \in \Gamma. \end{cases}$$

- The fact that the limiting  $(N \to \infty)$  dynamics may have multiple stable equilibria implies that our system exhibits what is called *phase transition:*.
  - $\rightarrow$  The asymptotic  $(N \rightarrow \infty)$  behavior of the system changes depending on the values of the parameters (and of the initial conditions).
  - $\rightarrow$  The *effects of phase transition* for the system with finite N can be seen on *different time scales* in different ways.

 On regular time-scales (of order O(1)) the following occurs: for certain values of the initial condition the system is driven towards the asymptotic symmetric equilibrium state (0,0) where half of the firms are in good financial health.

After a certain time (depending on the initial condition) the system is captured by an unstable direction of this neutral equilibrium and moves towards a stable asymmetric equilibrium. *During this transition the volatility of the system (will be defined below) increases sharply* before decaying to a stationary value.

→ This phenomenon can be interpreted as a credit crisis and may account for default clustering.



Figure 1:  $\beta=1, \gamma=2.3, \gamma_c=1/tanh(\beta)\approx 1.313$ 



## Figure 2: $\beta = 1.5, \gamma = 2.1, \gamma_c = 1/tanh(\beta) \approx 1.105$



### Figure 3: $\gamma_c \approx 1.105$ ; $\gamma_c \approx 1.396$



### C. Analysis of the fluctuations

- Concerns the asymptotic distribution of  $(\rho_N Q^*)$ .
  - $\rightarrow$  Recall that  $\rho_N(t)$ , being a measure on  $\{-1,1\}^2$ , is characterized by

$$m^{\sigma}_{\rho_N}(t), \ m^{\omega}_{\rho_N}(t), \ m^{\sigma\omega}_{\rho_N}(t)$$

• With A(t), D(t) appropriate matrices depending on  $\beta, \gamma$  and  $m_t^{\sigma}, m_t^{\omega}, m_t^{\sigma\omega}$  one has the following

Theorem 3. Let

$$\begin{cases} x_N(t) = \sqrt{N} \left( m_{\rho_N}^{\sigma}(t) - m_t^{\sigma} \right) \\ y_N(t) = \sqrt{N} \left( m_{\rho_N}^{\omega}(t) - m_t^{\omega} \right) \\ z_N(t) = \sqrt{N} \left( m_{\rho_N}^{\sigma\omega}(t) - m_t^{\sigma\omega} \right) \end{cases}$$

Then  $(x_N(t), y_N(t), z_N(t)) \xrightarrow{N \to \infty} (x(t), y(t), z(t))$  in the sense of weak convergence of stochastic processes, where (x(t), y(t), z(t)) is a centered Gaussian process, unique solution of the linear SDE

$$\begin{pmatrix} dx(t) \\ dy(t) \\ dz(t) \end{pmatrix} = A^*(t) \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} dt + D(t) \begin{pmatrix} dB_1(t) \\ dB_2(t) \\ dB_3(t) \end{pmatrix}$$

where  $B_1, B_2, B_3$  are independent Brownian motions and (x(0), y(0), z(0)) is a centered Gaussian.

 $\rightarrow$  The asymptotic, for  $N \rightarrow \infty$ , distribution of  $(x_N(t), y_N(t), z_N(t))$  is thus, for each fixed t, a centered Gaussian with covariance matrix  $\Sigma_t$  - the volatility referred to earlier - satisfying (asymptotics in t depend upon  $\gamma$ )

$$\frac{d\Sigma_t}{dt} = A(t)\,\Sigma_t + \Sigma_t\,A^*(t) + DD^*(t)$$

**Corollary 1:**  $\sqrt{N} \left[ m_{\rho_N}^{\sigma}(t) - m_t^{\sigma} \right] \xrightarrow{D} \mathcal{N}(0, \Sigma_t^x)$  so that (notice that  $m_N^{\underline{\sigma}}(t) = m_{\rho_N}^{\sigma}(t)$ )

$$P(m_{N}^{\underline{\sigma}}(t) \ge \alpha) \approx \Phi\left(\frac{\sqrt{N}m_{t}^{\sigma} - \sqrt{N}\alpha}{\sqrt{\Sigma_{t}^{x}}}\right)$$

 $(\Phi(\cdot) \text{ cumulative standard Gaussian}).$ 

### **Portfolio losses**

- A bank holds a portfolio of financial positions issued by the N firms.
- Random loss for the i th position at time t:

$$L_i(t) \in \mathbb{R}^+; \quad i = 1, \dots, N$$

• Aggregated losses are  $L^{N}(t) = \sum_{i=1}^{N} L_{i}(t)$ 

• More specifically, let

 $G_x(u) := P\{L_i(t) \le u \mid \sigma_i(t) = x\}, \quad x \in \{-1, +1\}$ 

(homogeneity with respect to i and t) and

$$\ell_1 := E\{L_i(t) \mid \sigma_i(t) = 1\} < E\{L_i(t) \mid \sigma_i(t) = -1\} := \ell_{-1}$$

 $\rightarrow$  one expects to loose more when in financial distress.

Furthermore,

$$v_1 := Var\{L_i(t) \mid \sigma_i(t) = 1\}; v_{-1} := Var\{L_i(t) \mid \sigma_i(t) = -1\}$$

### Example 1

• Portfolio consisting of N positions of 1 unit due at time T (defaultable bonds).

$$L_i(T) = L(\sigma_i(T)) = \begin{cases} 1 & if \quad \sigma_i(T) = -1 \\ 0 & if \quad \sigma_i(T) = 1 \end{cases}$$

$$\longrightarrow \qquad L^{N}(T) = \sum_{i=1}^{N} \frac{1 - \sigma_{i}(T)}{2} = \frac{N(1 - m_{N}^{\sigma}(T))}{2}$$
$$\longrightarrow \qquad P\{L^{N}(T) \ge \alpha\} = P\{m_{N}^{\sigma}(T) \le 1 - \frac{2\alpha}{N}\}$$
$$apply Corollary 1$$

#### A further result

• Let  

$$L(t) := \frac{(\ell_1 - \ell_{-1})}{2} m_t^{\sigma} + \frac{(\ell_1 + \ell_{-1})}{2}$$

$$V(t) := \frac{(\ell_1 - \ell_{-1})^2 \Sigma_t^x}{4} + \frac{(1 + m_t^{\sigma}) v_1}{2} + \frac{(1 - m_t^{\sigma}) v_{-1}}{2}$$

**Theorem 4:** When the distribution of  $L_i(t)$  depends on  $\sigma_i(t)$ ,

$$\sqrt{N}\left(\frac{L^N(t)}{N} - L(t)\right) \xrightarrow{D} \mathcal{N}\left(0, V(t)\right)$$

**Corollary 2:** In the setting of Theorem 4 it follows

$$P\left\{L^{N}(T) \geq \alpha\right\} \sim \Phi\left(\frac{NL(T) - \alpha}{\sqrt{N}\sqrt{V(T)}}\right)$$

### *Example 2* (Bernoulli mixture model)

• As before but with

$$L_{i}(T) = L(\sigma_{i}(T); \Psi) = \begin{cases} 1 & with \ prob \quad P(\sigma_{i}(T); \Psi) \\ 0 & with \ prob \quad 1 - P(\sigma_{i}(T); \Psi) \end{cases}$$

where  $\Psi$  is an exogenous random factor.

$$\rightarrow \ \ell_1 = P(1; \Psi), v_1 = P(1; \Psi)(1 - P(1; \Psi)) \text{(analogously for } \ell_{-1}, v_{-1})$$

• A possible specification is

$$P(\sigma; \Psi) = 1 - \exp\{-k_1\Psi - k_2(1-\sigma)/2 - k_3\}$$

with  $k_i \ge 0$  and  $\Psi \sim \Gamma(\alpha; \kappa)$ . (The prob. for  $L_i(T) = 1$ is bigger for  $\sigma_i(T) = -1$  than for  $\sigma_i(T) = 1$ ).  Here l<sub>1</sub>, l<sub>-1</sub>, v<sub>1</sub>, v<sub>-1</sub> and thus also L(t) and V(t) depend on the value ψ taken by the Gamma-type r.v. Ψ. Denote the latter by L(t; ψ), V(t, ψ).

 $\rightarrow$  by Corollary 2

$$P\left\{L^{N}(T) \geq \alpha\right\} \sim \int \Phi\left(\frac{NL(T;\psi) - \alpha}{\sqrt{N}\sqrt{V(T;\psi)}}\right) df_{\Psi}(\psi)$$

with  $f_{\Psi}(\cdot)$  the Gamma-density of  $\Psi$ .

### Figure 4: $\beta = 1.5, \gamma = 2.1, \gamma_c = 1/tanh(\beta) \approx 1.105$



Figure 5:  $\gamma_c = 1/tanh(1.5) \approx 1.105$ ;  $\gamma_c = 1/tanh(0.9) \approx 1.396$ 

